

Monday, April 12

Announcements:

→ HW 5 due Wednesday

Topic 15 - Particle Swarm Optimization

In all of our MH so far: we have always tracked a single solution moving through the search space.

Particle Swarm Opt. (PSO) is our first "population MH" - we will track many candidates at a time and they will interact with each other.

Idea: You have N particles, each representing a candidate in the search space. They all start at random positions.



random candidates.

Each particle has a velocity that depends on three things:

- (1) current velocity (inertia)
- (2) the best solution that particle has ever seen before
- (3) the best solution that any particle has ever seen before.

Let $x_i(t)$ and $v_i(t)$ denote the position and velocity of particle i at time t .

$$x_i(t+1) = x_i(t) + v_i(t+1)$$

(the velocity dictates how the position changes)

$$v_i(t+1) = \underbrace{\alpha \cdot v_i(t)}_{\text{inertia}} + \beta \cdot r_1 \cdot (b_i(t) - x_i(t)) + \gamma \cdot r_2 \cdot (B(t) - x_i(t))$$

diff. b/w and ^{now} personal best

diff b/w ^{now} and global best

α, β, γ : parameters

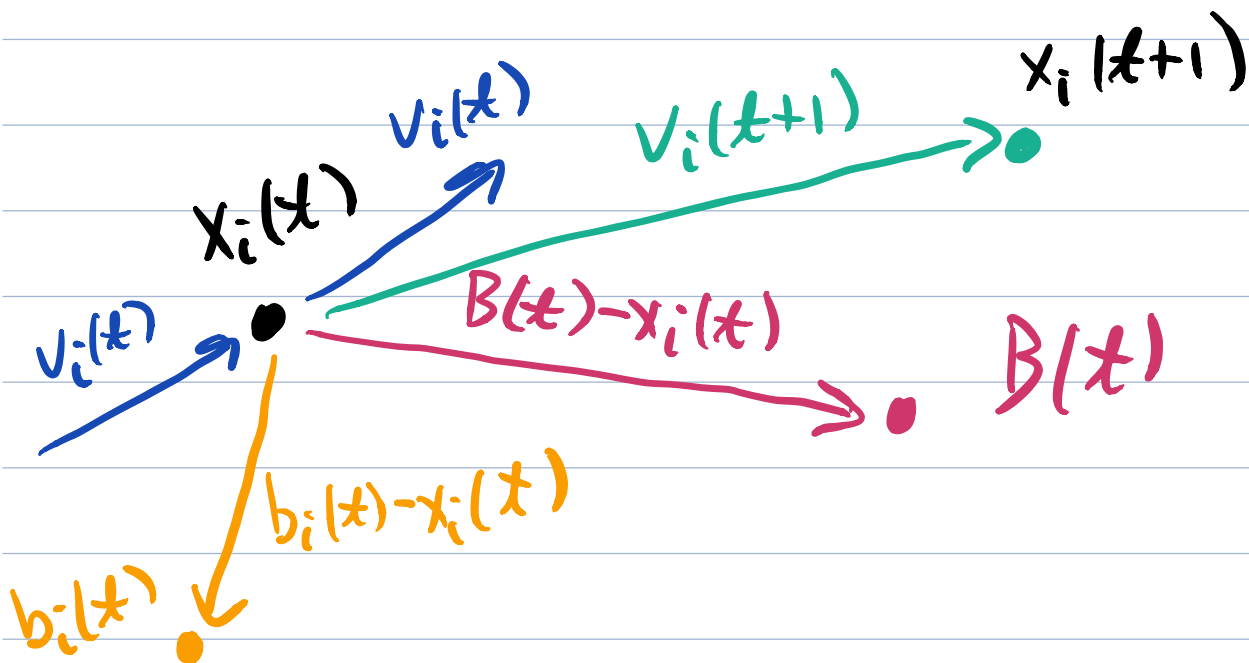
r_1 and r_2 : random vectors in $[0, 1]$

$b_i(t)$: best sol. particle i has ever seen up to time t

$B(t)$: best sol any particle has seen

up to time t .

α : weighting factor for inertia ≈ 0.9
 β, γ : weighting factors for personal/global best ≈ 0.95



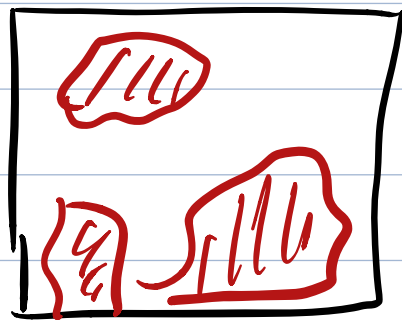
We need to have a meaning for subtracting solutions in the search space.

Continuous optimization: \mathbb{R}^d

$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} - \begin{bmatrix} d \\ e \\ f \end{bmatrix} = \begin{bmatrix} a-d \\ b-e \\ c-f \end{bmatrix}$$

Problem: What do you do if your particles run away?

* You need to keep your particles in regions that satisfy the constraints.
→ Could be nice bounds, $-2\pi \leq x, y \leq 2\pi$, or worse like in the spring problem.



→ What do you do if your particle moves into an invalid spot?