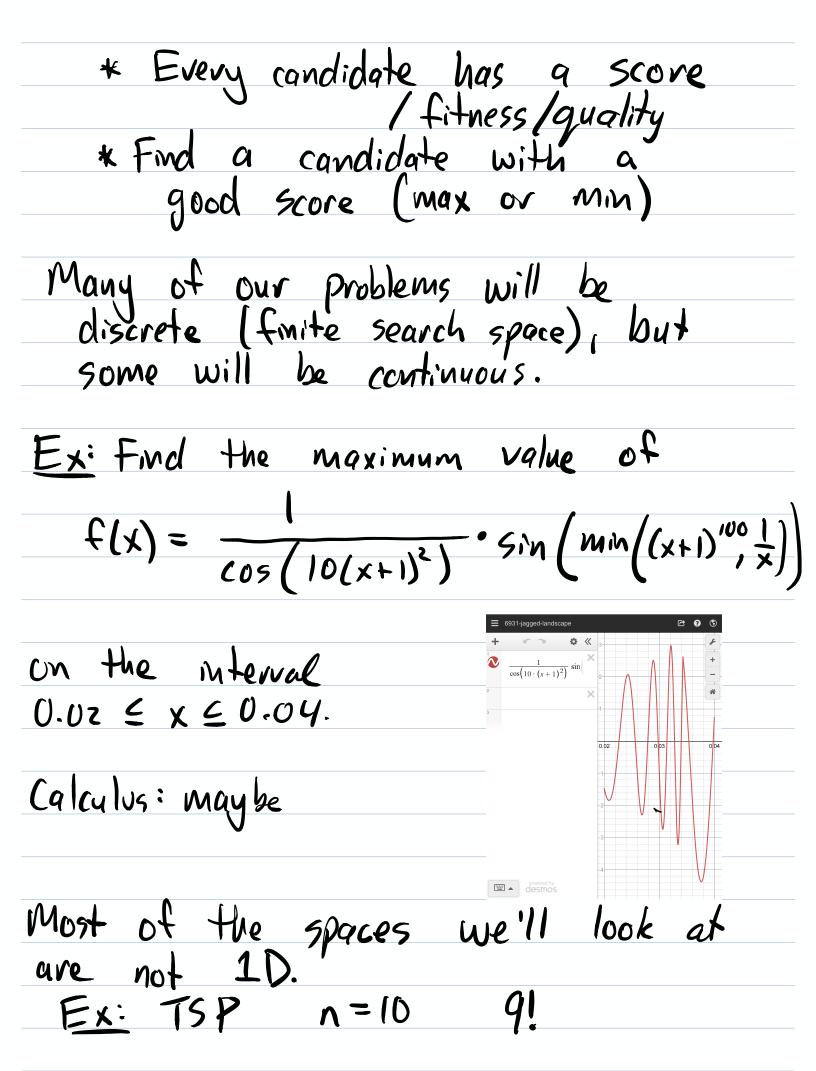
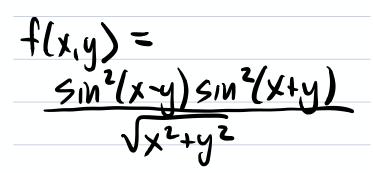


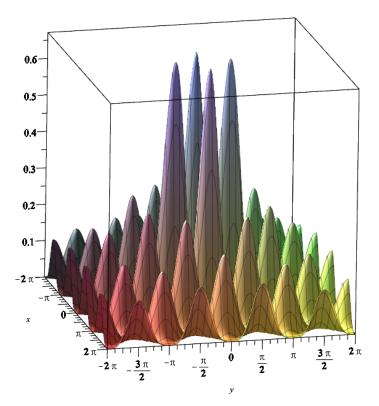
Friday, March 19 Lecture #23
Topic 11 - Introduction to Metaheuristics
We've mostly focused on finding optimal solutions.  Problem: these methods are hard and not always applicable
solutions.
Problem: these methods are hard and
not always applicable
Ex: TSP takes O(n2-2n) time for dynamic programming.
for dynamic programming.
<b>' ' ' ' ' ' ' ' ' '</b>
Metaheuristics:
- Gorgood Souldons on live Consolings
that can be easily adapted
to many problems.
that can be easily adapted to many problems.  - Look for good solutions, not optimal ones - Pretty fast
optimal ones
- Pretty fast
Similar Setup:
* Search space of condidates/
Similar Setup:  * Search space of candidates/ Solutions



## "landscape pictures"



Goal: find the top of the tallest hill, but not get stuck on the wrong hill-top.



## Gradient Ascent ("Descent")

\* Optimization method (not a M-H) \* If your function f(x,y) is diffible, you can compute the gradient at a point.

Gradient is a vector that points you in the direction of steepest ascent.

(1) Start at a Doint
(1) Start at a point  >(2) compute the gradient  (3) move a little in that direction  (4) repeat
(3) more a little in that direction
(4) recent